# SERIES F18

# **Dynapar**<sup>™</sup> brand

## For Stepper & Small Servo Motors

## **Key Features**

- Under 2.0" Diameter Package with High 10,000PPR Capability
- Easy to Install Hollowshaft and Spring Tether Design
- Up to 120°C Temperature Range Doesn't Limit Motor Performance





### **SPECIFICATIONS**

#### STANDARD OPERATING CHARACTERISTICS

**Code:** Incremental with commutation option, Optical

**Resolution:** 500, 512, 1000, 1024, 2000, 2048, 2500, 4096, 5000, 8192, 10,000 PPR incremental with 4, 6, 8 or 12 pole commutation channels

**Accuracy:** Incremental: ±2.5 arc-mins. max. edge to any edge; Commutation: ±6 arc-mins. max

Phasing for CCW rotation of motor shaft (viewing encoder cover): A leads B by 90° and U leads V leads W by 120°.

Minimum edge separation A to B is 45°.

**Index to U channel:** +/- 1 °mech. index pulse center to U channel edge.

Index Pulse Width: 90° gated A and B high; (180° gated B high gating options available consult factory)

#### ELECTRICAL

Input Power Requirements: 5±10% VDC at 150 mA max (incremental only); 175 mA max. (incremental and commutation), excluding output load

#### **Output Signals:**

Line Driver: sink / source 40 mA max., Open Collector Incremental (  $\leq$  2048 PPR): 16 mA sink max.

Open Collector Commutation: 30 mA sink max. (2.0  $k\Omega$  pull-ups in encoder)

#### Frequency Response:

PPR ≤ 2048: 250 kHz; PPR > 2048: 500 kHz

**Termination:** 16 pin, fully shielded, 2mm pitch, double row header. Accessory mating cable assembly available: 26 AWG twisted pair, jacketed and shielded with copper drain wire

#### **MECHANICAL**

Weight: 4 oz. (110 gm) typ.

**Dimensions:** Outside Diameter with cover: 1.96" (49.8mm), without cover 1.85" (47.0mm); Outside collar height 1.71" (43.4mm), inside collar height 1.50" (38.1mm)

**Material:** Bearing housing: aluminum; Cover: high temperature, glass filled polymer;

Hub: Brass; Disk: 0.030" thick glass **Finish**: Cover: RAL 7010 (dark grey)

Moment of Inertia: 5.3X10<sup>-4</sup> in-oz sec.<sup>2</sup> (37.3 gm-cm<sup>2</sup>)

**Hub Diameters:** 1/4", 3/8", 7/16", 1/2", 6mm, 8mm,10mm,12mm standard

**Bore Dia. Tolerance:** +0.001"/-0.000" (+0.025 mm/ -0.000 mm)

Mating Shaft Length: 1.62" (41 mm) minimum for outside shaft collar. 0.50 inch minimum for inside shaft collar.

Mating Shaft Runout: 0.002" (0.05 mm) max. (Includes shaft perpendicularity to mounting

Mating Shaft Axial movement: ±0.060" (±1.52 mm)

**Mounting:** Four standard configurations are available for tethers. A choice of U.S. and Metric screws are included. Mounting holes should be 0.01" (0.254 mm) true position to shaft for best encoder operation.

**Shaft clamp:** 2 #6-32 set screws in collar around hub shaft (will not mar shaft) Electrical/Mechanical Alignment Range:

 $\pm 15^{\circ}$  mechanical typical (see tether options) **Acceleration:** 100,000 rad/sec.<sup>2</sup> max.

**Max. Velocity:** RPM= (Frequency / PPR)x 60; or 12,000 RPM, whichever is less;

**Bearing Life:**[(3.6 X 10<sup>9</sup>) / RPM] Hours; e.g. 605,000 hours @6,000 RPM

(Based on bearing manufacturer's suggested calculation for 6803ZZ with 37N equivalent dynamic load - including preload and tether reaction loads - at 6000 RPM continuous with adequate lubrication)

#### **ENVIRONMENTAL**

Operating Temperature: 0° to +120°C Storage Temperature: -40° to +120°C Shock: 100 Gs for 6 msec duration Vibration: 2.5 Gs at 5 to 2000 Hz Relative Humidity: 90% non-condensing

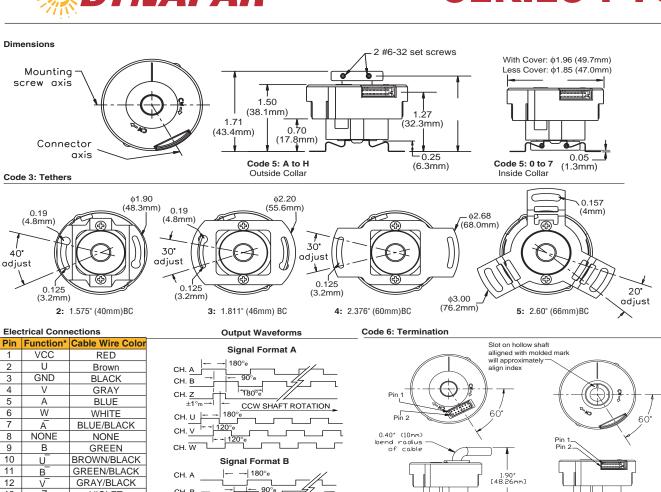
Enclosure Rating: NEMA 1 / IP40 (for models

with cover)



## SERIES F18

**Z, A, B** Radial Connector JST #S16B-PHDSS



Z NONE Function availability dependant on Model

VIOLET

WHITE/BLACK

VIOLET/BLACK

NONE

CH. B

CH Z

CH. U = 60°e

+60°€

#### Mating Cable Assembly:

W

13

14

15

16

Incremental only, 111752-000x Incremental + Comm., 111753-000x

#### **Ordering Information**

CCW SHAFT ROTATION

0, 1, 2 Axial Connector JST #B16B-PHDSS

H 12 mm

180°e

x= le	ength in feet	To order, complet		ber with code numbers from the	ne table below:				
Code 1: Model		Code 2: PPR, Poles	Code 3: Tether	Code 4: Electrical	Code 5: Shaft/Bore	Code 6: Termination			ation
F18									
Ordering Information									
F18	Size 18 Commutating Encoder	Incremental channels only 0500/0 2500/0 0512/0 4096/0	0 No Tether 2 2 #2 on 1.575" Diameter	Available when Code 2 is ≤ 2048/0  0 5V in, open collector out incremental only c 5V in, open collector out incremental only - reverse phase  Available when Code 2 is XXXX/0  3 5V in, line driver out incremental only D 5V in, line driver out incremental only - reverse phase  Available when Code 2 is XXXX/4, XXXX/6, XXXX/6 xXXXX/6  5V in, line driver out for incremental; 5V in, open collector out for commutation  E 5V in, line driver out for incremental; 5V in, open collector out for commutation  collector out for commutation - reverse phase	Inside Collar:  0 1/4 in. 1 3/8 in. 2 7/16 in. 3 1/2 in. 4 6 mm 5 8 mm 6 10 mm 7 12 mm	Code Connector/Cable Wire Axial Radial Pigtal			Length
		1000/0   5000/0   1024/0   8192/0   2000/0   10E3/0*   2048/0   * = 10000/0	3 2 #4 on 1.811" Diameter 4 2 #4 on 2.376" Diameter 5 3 #4 on 2.60" Diameter 7 2 M2.5 on 40 mm Diameter 8 2 M3 on 46 mm Diameter 9 2 M3 on			0 1 2 3 4 5 6	Z A B C D E F	N/A J K L M P	None 1 Ft. 2 Ft. 3 Ft. 4 Ft. 5 Ft. 6 Ft. 7 Ft.
		1000/† 5000/† 1024/† 8192/† 2000/† 10E3/†* 2048/† *= 10000/†			Outside Collar:  A 1/4 in. B 3/8 in. C 7/16 in.	8 C0			
† Available with 4, 6, Examples: 1024/8 is 8 or 12 pole. (12 pole 1024PPR, 8 pole; is designated by 2000/C is 2000PPR, character "C") 12 pole			60 mm Diameter A 3 M3 on 66 mm Diameter	9 5V in, line driver out for incremental; 5V in, line driver out for commutation F 5V in, line driver out for incremental; 5V in, line driver out for commutation - reverse	D 1/2 in. E 6 mm F 8 mm G 10 mm	connector mounted in axial or radial position. Available with or without mating connector/cable. Alternativly, a direct-solder pigtail cable is offered.			